

The Dynamical Systems Model of the Simple Genetic Algorithm

7. Crossover and the Mixing-Matrix

- The effects of crossover in terms of an operator C acting upon Λ .

· Given a population $p \in \Lambda$, $(Cp)_k$ will give the probability of individual z_k being in the next population.

$$\cdot G = C \circ U \circ F$$

- For all the usual kinds of crossover, the order of crossover and mutation doesn't matter.

· combination of mutation and crossover gives *mixing scheme* for the GA

$$\cdot M = C \circ U = U \circ C .$$

$$\cdot G = M \circ F$$

- Some properties of crossover operator C

· $\omega(p, q) \in \Lambda$: population distribution resulting from crossing over random parents from distributions p and q .

· $\omega(p, q)_k = \sum_{i,j} p_i q_j \omega(e_i, e_j)_k$: probability that crossing z_i and z_j will produce z_k .

· ω is an bilinear operator

$$\cdot C(p) = \omega(p, p) = \sum_{i,j} p_i p_j \omega(e_i, e_j)$$

$$\cdot C(\alpha p) = \omega(\alpha p, \alpha p) = \alpha \omega(p, \alpha p) = \alpha^2 \omega(p, p) = \alpha^2 C(p)$$

$$\cdot G(p) = (M \circ F)(p) = (C \circ U \circ F)(p)$$

$$= C\left(\frac{1}{\bar{f}(p)} USp\right) = \frac{1}{(\bar{f}(p))^2} C(USp) = \frac{1}{(\bar{f}(p))^2} M(Sp)$$

· C can be defined using s matrices, one for each individual z_k .

$$C(p)_k = \sum_i p_i \sum_j \omega(e_i, e_j)_k p_j = p \cdot (C_k p)$$

· Utilizing the symmetry of crossover action, C can be written in terms of the matrix C_0 and a set of permutation matrices σ_k

$$C(p)_k = (\sigma_k p) \cdot C_0 (\sigma_k p) = \sigma_k^T C_0 \sigma_k \quad \text{where } \sigma_k = \begin{cases} 1 & \text{if } z_i \oplus z_k = z_j \\ 0 & \text{otherwise} \end{cases}$$

- The *mixing scheme*

$$M(p)_k = C(U p)_k = (U p) \cdot (C_k U p) = p \cdot (U C_k U p)$$

$$= p \cdot (U \sigma_k^T C_0 \sigma_k U p) = (\sigma_k p) \cdot (U C_0 U \sigma_k p) = (\sigma_k p) \cdot (M_0 \sigma_k p)$$

where $M_k = U C_k U$.

8. Mixing and the Walsh Transform

- The Walsh transform

$$\cdot W_{i,j} = \frac{1}{\sqrt{s}} (-1)^{z_i \cdot z_j} \text{ for } i, j = 0, \dots, (s-1).$$

- gives us an efficient way to calculate the effects of the operator M .
- to calculate $G(p)$, we need to calculate the Walsh transform of $M(p)$, which can be calculated easily using Walsh transform of $F(p)$
- if initial population is chosen uniformly at random from the search space, Walsh transform of $F(p)$ is consisted of fitnesses of each individual.

9. Properties and Conjectures Concerning G

- Principle conjecture

- G is *focused* under assumptions about crossover and mutation.
- Given any population vector, the sequence $p, Gp, G^2 p, \dots$ converges
- Assumptions:
 - * Bitwise mutation with a mutation rate < 0.5 and no crossover.
 - * Linear fitness function and small mutation rate, when there is crossover.

- Second conjecture

- Fixed-points of G will be *hyperbolic* for nearly all fitness functions.
- A fixed-point is said to be hyperbolic if the differential of G at the point has no eigenvalue with modulus equal to 1.
- True for fixed-length binary strings, proportionate selection, any kind of crossover, and mutation defined bitwise with a positive mutation rate.

- Properties of G from above conjectures

- There are only finitely many fixed-points of G .
- The probability of picking a population p , s.t. iterates of G applied to p converge on an unstable fixed-point, is zero.
- The infinite population GA converges to a fixed-point in logarithmic time.